FP93

Program Controller

Instruction Manual

Thank you for purchasing a Shimaden product. Please check that the delivered product is the correct item you ordered. Please do not begin operating this product before you read this instruction manual thoroughly and understand its contents.

"Notice"

Please ensure that this instruction manual is given to the final user of the instrument.

"Preface"

This instruction manual is meant for those who will be involved in the wiring, installation, operation and routine maintenance of the FP93. It describes matters to be attended to in handling the FP93, how to install it, wiring, its functions and operating procedure. Keep this manual at the work site while handling the instrument and follow the guidance provided herein

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1. Safety Rules

For matters regarding safety, potential damage to equipment and/or facilities, additional instructions and notes are indicated by the following headings.

MARNING

This heading indicates hazardous conditions that could cause injury or death of personnel unless extreme caution is exercised.

⚠ CAUTION

This heading indicates hazardous conditions that could cause damage to equipment and/or facilities unless extreme caution is exercised.

Note

This heading indicates additional instructions and/or notes.

The mark (a) represents a protective conductor terminal. Make sure to ground it properly.

↑ WARNING

The FP93 is designed for controlling temperature, humidity and other physical quantities of general industrial equipment. Avoid using it for control of devices which may seriously affect the human life. When used, adequate and effective safety measures must be taken. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.

⚠ WARNING

- For using this instrument, house it in a control box or the like lest terminals should be in contact with a person.
- Don't draw out the instrument from the case. Don't let your hand or a conductive body in the case. It may lead to serious
 injury or death due to an electric shock.
- Make sure to ground protective conductor terminals.

⚠ CAUTION

To avoid damage to connected equipment, facilities or products due to a fault of the product, safety measures must be taken before usage, such as the installation of a fuse, an overheating protection device and the like. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.

⚠ CAUTION

- The \bigwedge mark on the plate affixed to the instrument:
 - On the terminal nameplate affixed to the case of this instrument, the alert mark \triangle is printed. This is to warn you of the risk of electric shock which may result if the charger is touched while being energized.
- As a means to turn the power off, a switch or a breaker should be installed in the external power circuit to be connected to the power terminal of the instrument. Fix the switch or the breaker adjacently to the instrument in a position which allows it to be operated with ease, with an indication that it is a means of turning the power off. Use a switch or a breaker which meets the requirement of IEC60947.
- Fuse:

Since the instrument does not have a built-in fuse, do not forget to install a fuse in the power circuit to be connected to the power terminal. A fuse should be positioned between a switch or a breaker and the instrument and mounted on the L side of the power terminal.

Fuse rating/characteristics: 250V AC 1A/medium lagged or lagged type.

Use a fuse which meets the requirement of IEC60127.

- Voltage/current of a load to be connected to the output terminal and the alarm terminal should be within a rated range. Otherwise, the temperature will rise to reduce the life of product and/or to result in problems with the product. For rated voltage/current, see "9. Specifications" of this manual.
 - The output terminal should be connected with a device which meets the requirements of IEC61010.
- A voltage/current different from that of the input specification should not be applied to the input terminal. It may reduce the life of the product and/or result in problems with the product. For rated voltage/current, see "9. Specifications" of this manual.

In the case of voltage or current input, the input terminal should be connected to a device which meets the requirement of IEC61010.

The instrument is provided with a draft hole for heat discharge. Take care to prevent metal and other foreign matters from getting into it. Failure to do so may result in trouble with the instrument or may even cause a fire.

- Don't block the draft hole or allow dust or the like to stick to it. A rise in temperature or insulation failure may result in a reduction of the life of the product and/or problems with it or may cause a fire.
 - For spaces between installed instruments, refer to "3-3. External Dimensions and Panel Cutout."
- It should be noted that repeated tolerance tests against voltage, noise, surge, etc. may lead to deterioration of the instrument.
- Users are prohibited from remodeling the product or abnormal use of it.

2. Introduction

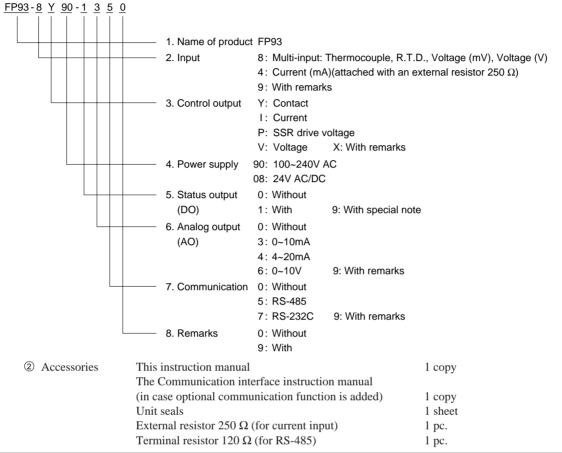
2-1. Check before Use

This product has been fully inspected for quality assurance prior to shipment. Nevertheless, you are requested to make sure that there is no error, damage or shortage of delivered items by checking the model codes and the external view of the product and the number of accessories.

① Confirmation of Model Codes

Check the model codes stuck to the case of the product to ascertain if the respective codes designate what were specified when you ordered it, referring to the following code table:

Example of model codes:



NOTE: For any problem with the product, shortage of accessories or request for information, please contact our sales agent.

2-2. Handling Instruction

- ① Don't operate the keys on the front panel with a hard or sharply pointed object. Operate the keys only by softly touching them by your fingertips.
- ② When cleaning the instrument, wipe it gently with a dry cloth. Never use solvent such as a thinner.

3. Installation and Wiring

3-1. Installation Site (environmental conditions)

⚠ CAUTION

This instrument should not be used in any of the places mentioned below. Selection of these places may result in trouble with the instrument, damage to it or even a fire.

- ① Where flammable gas, corrosive gas, oil mist and particles that can deteriorate electrical insulation are generated or abundant.
- ② Where the temperature is below -10° C (14° F) or above 50° C (122° F).
- 3 Where the relative humidity is above 90%RH or below dew point.
- 4 Where highly intense vibration or impact is generated or transferred.
- (5) Near high voltage power lines or where inductive interference can affect the operation of the instrument.
- 6 Where the instrument is exposed to dew drops or direct sunlight.
- 7 Where the height is above 2000 m.
- 8 Outdoors.
- (9) Where the instrument is exposed to the flow of blowing air.

NOTE: The environmental conditions belong to the installation category II of IEC60664 and the degree of pollution is 2.

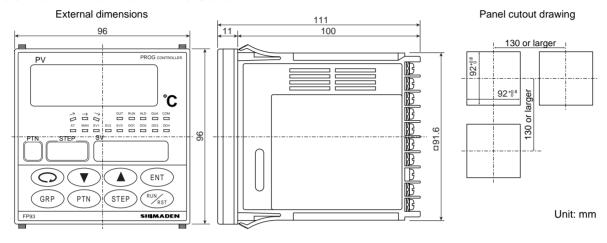
3-2. Mounting

⚠ CAUTION

For safety's sake and to protect the functionality of the product, don't draw out its body from the case. If it needs to be drawn out for replacement or repair, contact our sales agent.

- ① Cut a hole for mounting the controller in the panel by referring to the cutout drawing in Section 3-3.
- ② The panel thickness should be 1.0~4.0 mm.
- ③ As the instrument is provided with pawls for fixing, just press it firmly from the front of the panel. The case is fixed to the panel by means of the pawls.
- ④ The FP93 is designed as a panel-mounting model. Never use it without mounting on the panel.

3-3. External Dimensions and Panel Cutout

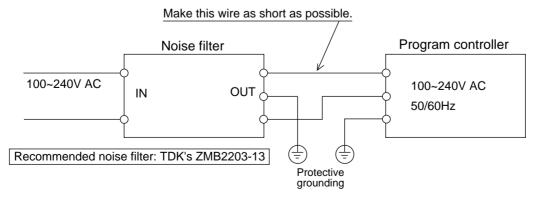


3-4. Wiring

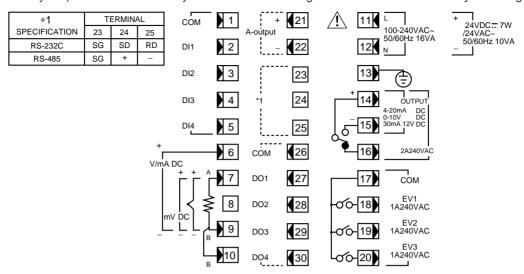
In wiring operation, close attention should be paid to the following:

♠ CAUTION

- Make sure to disconnect this instrument from any power source during wiring operation to prevent an electric shock.
- Be certain that the protective conductor terminal () is properly grounded. Otherwise, an electric shock may result.
- To prevent an electric shock, don't touch wired terminals and other charged elements while they are being energized.
 - ① In wiring operation, follow the terminal layout shown in Section 3-5 and the terminal arrangement in Section 3-6 and make sure to carry out the correct wiring.
 - ② Use press-fit terminal which fits an M3.5 screw and has a width of 7 mm or less.
 - 3 In case of thermocouple input, use a compensating cable compatible with the selected type of thermocouple.
 - 4 In the case of R.T.D. input, the resistance of a single lead wire must be 5 Ω or less and the three wires must have the same resistance.
 - (§) The input signal wire must not be accommodated with a high-voltage power cable in the same conduit or duct.
 - 6 Shield wiring (single point grounding) is effective against static induction noise.
 - ① Twisting the input wires at short and equal intervals is effective against electromagnetic induction noise.
 - In wiring for power supply, use a wire or cable whose performance is equal to or higher than the 600V vinyl insulated wire having a sectional area of 1 mm² or larger.
 - 9 The wire for grounding must have a sectional area of 2 mm² or larger and must be grounded at a grounding resistance of $100~\Omega$ or less.
 - © Clamp the screws of terminals firmly. Clamping torque: 1.0 N ⋅ m (10kgf ⋅ cm)
 - 1 If the instrument appears to be easily affected by power supply noise, use a noise filter to prevent malfunctioning.
 - ② Mount the noise filter on the grounded panel and make wire connection between the noise filter output and the power line terminals of the controller as short as possible.



3-5. Terminal Layout (Follow the terminal layout and terminal arrangement table shown below in your wiring operation.)

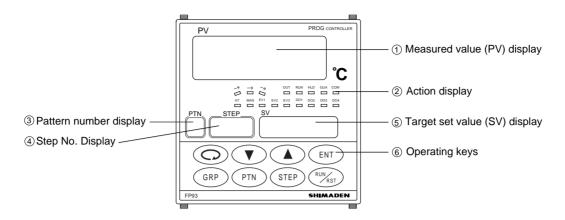


3-6. Terminal Arrangement Table

Name of terminal	Description/Code	Terminal No.
Power supply	100~240V AC/24V AC: L, 24V DC: + 100~240V AC/24V AC: N, 24V DC: -	11 12
Protective conductor	Protective grounding	13
Input	Voltage (V) Current (mA): + R.T.D.: A, thermocouple/Voltage (mV): + R.T.D.: B, thermocouple/Voltage (mV, V), Current (mA): - R.T.D.: B	6 7 9 10
Control output	Contact: COM, SSR drive voltage/Voltage/Current: + Contact: NO, SSR drive voltage/Voltage/Current: - Contact: NC	14 15 16
Event output	COM EV1 EV2 EV3	17 18 19 20
Analog output (option)	+ -	21 22
Communication (option)	SG RS-232C: SD, RS-485: + RS-232C: RD, RS-485: -	23 24 25
External control input	COM DII DI2 DI3 DI4	1 2 3 4 5
Status output (DO) (option)	COM DO1 DO2 DO3 DO4	26 27 28 29 30

NOTE 1: With thermocouple, voltage, or current input, shorting across B and B terminal will cause an error. Leave terminal No.10 open.

NOTE 2: With voltage (V) or current (mA) input, don't connect anything with terminal No.7. Any connection with it may cause problems with the instrument.

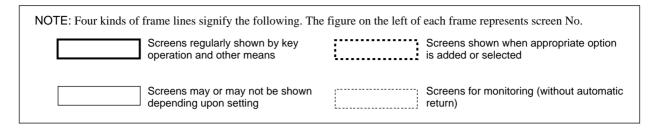


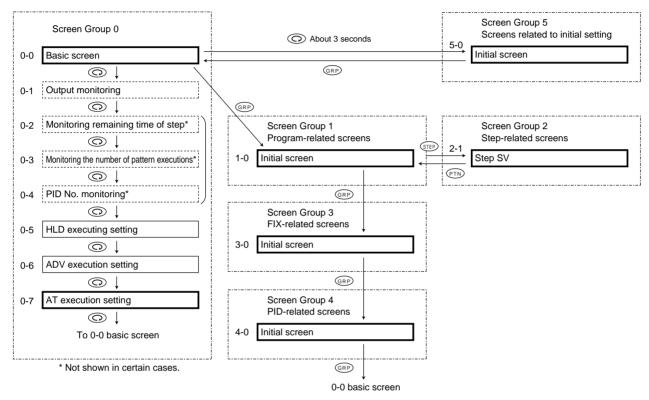
Name	Function
Measured value (PV) display	(1) Present measured value is displayed in the screen group 0. (red)(2) Type of parameter is shown on each parameter screen.
② Action display	 (1) → (green) Ascending action lamp Lights while ascending step is in execution. (2) → (green) Level action lamp Lights while level step is in execution. (3) → (green) Descending action lamp Lights while descending step is in execution. (4) OUT (green) Control output lamp Lights when contact or SSR drive voltage output is ON, goes out when output turns OFF. For current or voltage output, brightness increases or decreases in proportion to output. (5) RUN (green) RUN action lamp Lights while program is in execution. (6) HLD (green) HLD action lamp Lights when brief suspension (Hold) is set while program is in execution. (7) GUA (green) GUA action lamp Lights in case PV value does not reach a set range of deviation values when moving to level step during program execution (guarantee soak). (8) COM (green) Communication action lamp Lights when COM mode is selected in case the instrument includes the communication option. The lamp does not light if local is selected as communication mode. (9) AT (green) Auto tuning action lamp Blinks while AT is in execution. The lamp lights during standby for AT and goes out when AT action comes to an end or is terminated. (10) MAN (green) Manual control output action lamp Blinks when manual control output action lamp Blinks when manual control output. (11) EV1 (orange) Event 1 output action lamp. Lights when event 1 turns ON. EV3 (orange) Event 2 output action lamp. Lights when event 3 turns ON. EV3 (orange) Event 3 output action lamp. Lights when status output 1 turns ON. DO3 (green) Status output 1 action lamp. Lights when status output 1 turns ON. DO3 (green) Status output 3 action lamp. Lights when status output 1 turns ON. DO4 (green) Status output 3 action lamp. Lights when status output 4 turns ON. DO4 (green) Status output 4 action lamp. Lights when status output 4 tur
③ Pattern number display	(1) Pattern No. currently selected is displayed. (green)
④ Step No. Display	 Step No. currently in execution is displayed. (green) Step No. currently set in screen group 2 is displayed. PID No. currently set in screen group 4 is displayed.
⑤ Target set value (SV) display	 Target set value is displayed on the basic screen of screen group 0. (green) Present output value is displayed in % on the output monitor screen of screen group 0. Selected item and set value are displayed on each parameter screen.

Name	Function
Operating keys	(1)

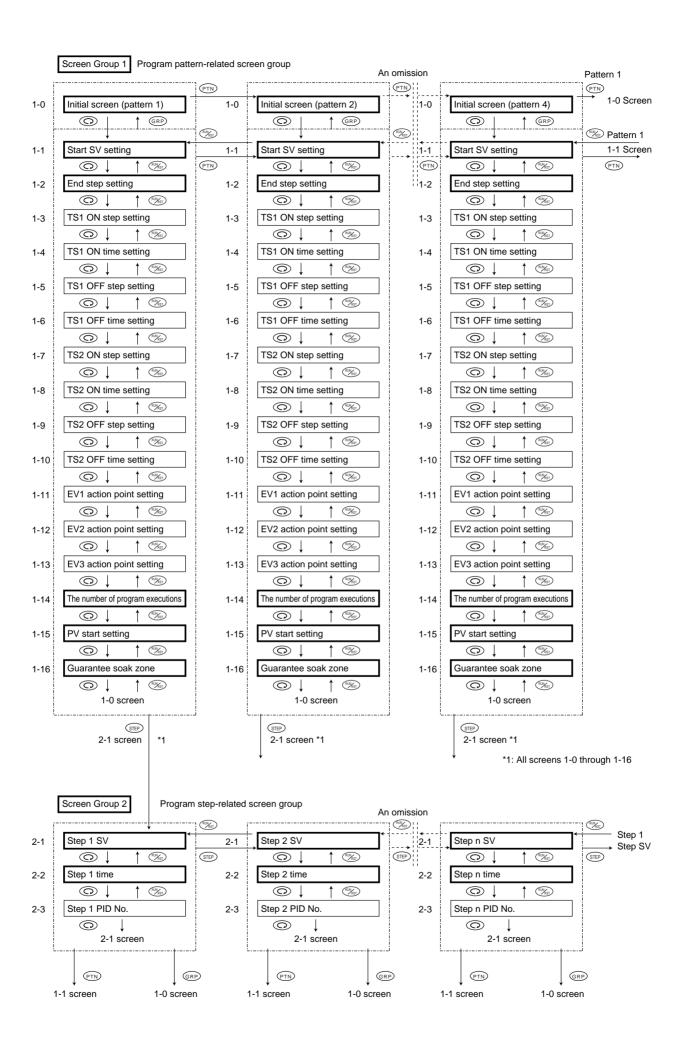
5. Explanation of Screens and Setting

5-1. Parameter Flow

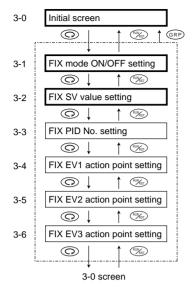


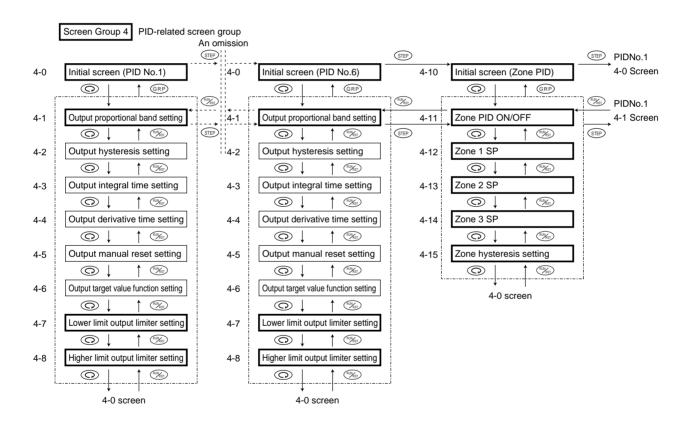


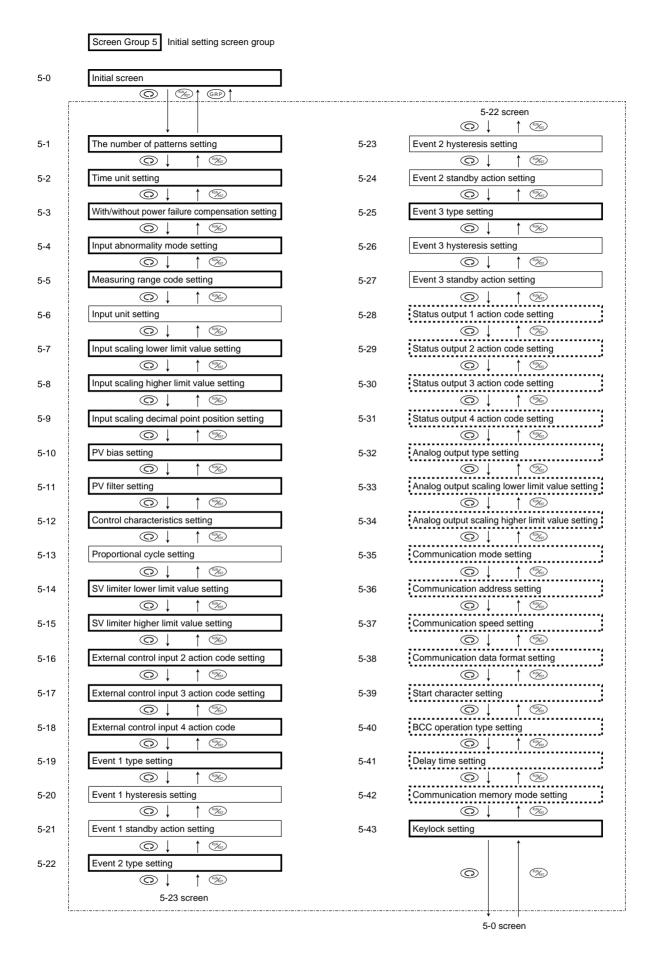
- (1) How to Move from Screen Group to Screen Group and Explanation of Screen Groups
- NOTE 1: To move among screen groups 0, 1, 3 and 4, press the Rep key on the basic screen of screen group 0 or the initial screens of screen group 1, 3 or 4.
- NOTE 2: To move between screen groups 0 and 5, pressing the key for 3 seconds continuously on the basic screen of screen group 0 calls the initial screen of screen group 5, and pressing the key on the initial screen of screen group 5 calls the basic screen of screen group 0.
- NOTE 3: Pressing the key in any screen group calls the next screen and pressing it on the last screen of a screen group calls the initial screen.
- NOTE 4: A key shown above and outside a chain line frame ([_____]) surrounding each screen group means that you can move from any of the screen within the frame to a designated screen by pressing that key. (This applies to screen groups 1, 2, 3, 4 and 5.) Example: Screen Group \(\)
- NOTE 5: The screen group 1 has patterns 1~4. (One pattern has 16 setting screens.) The number of patterns is selectable (which is set on the 5-1 screen; the initial value is 4).
- NOTE 6: The screen group 2 has steps 1 to 40 (one step containing three setting screens). The number of steps is selectable (which is set on the 1-2 screen; the initial value is 10).
- NOTE 7: The screen group 4 has 6 PID Nos. (each having 8 setting screens) and Zone PID.
- NOTE 8: Within a screen group, you can move from screen to screen by pressing an appropriate key indicated in screen sequences (which are shown in the following page on).



Screen Group 3 FIX-related screen group

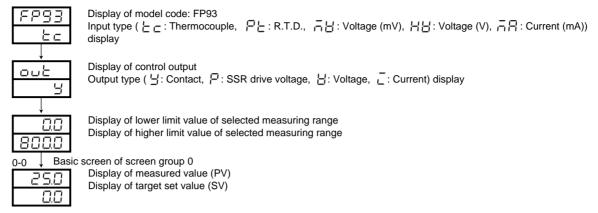






5-2. Application of Power and Display of Initial Screen

When power is applied, the initial screen and two screens are displayed successively, each for about 1 second as shown below. Then the basic screen is displayed.



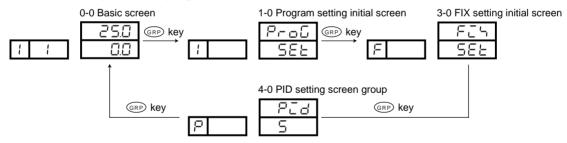
5-3 How to Change Screens

(1) How to Change Screen Groups 0~5

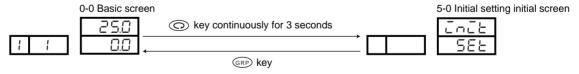
- Pressing the (GRP) key on the basic screen of screen group 0 calls the initial screen of screen group 1.
- Pressing the key on the basic screen of screen group 0 continuously for 3 seconds calls the initial screen of screen group 5.
- Pressing the STEP key on any screen of screen group 1 calls the 2-1 screen of screen group 2.
- Pressing the (GRP) key on the initial screen of screen group 1 calls the initial screen of screen group 3.
- Pressing the GRP key on any of the screens of screen group 2 calls the initial screen of screen group 1.
- Pressing the (GRP) key on the initial screen of screen group 3 calls the initial screen of screen group 4.
- Pressing the GRP key on the initial screen of screen group 4 calls the basic screen of screen group 0.
- Pressing the (GRP) key on the initial screen of screen group 5 calls the basic screen of screen group 0.
- Pressing the GRP key on any screen midway of screen group 0, 1, 3, 4 or 5 calls the initial screen of the screen group.
- Pressing the key on any screen midway of screen group 1, 2, 3, 4 or 5 calls the preceding screen.

 (Nevertheless, to return to the initial screen in screen group 1 or 4, you have to press the key or press the continuously to move to the last screen of the group before returning to the initial screen.

① How to move among 0~4 screen groups

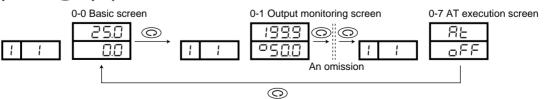


② How to move between screen group 0 and screen group 5



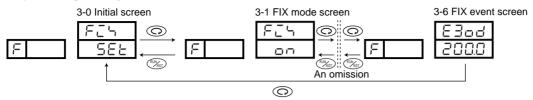
(2) How to Change Screen in Screen Group 0

Every time the key is pressed, the next screen is called, and the basic screen is called from the last screen.



(3) How to Change Screen in Screen Group 3

Every time the key is pressed, the next screen is called, and the basic screen is called from the last screen. Pressing the key calls the preceding screen.



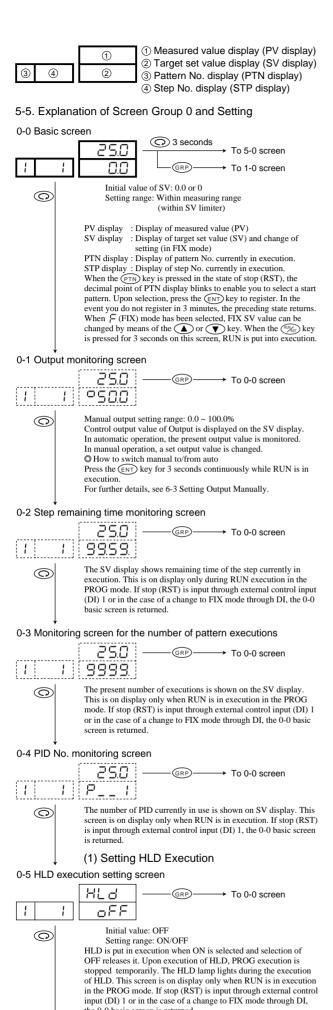
(4) How to Change Set Values (Data)

To change data on a screen which is called by pressing the key, use the for very key, and register the changed data by pressing the key.

5-4. Before Starting Up

To begin with, check the wiring and carry out the following on the respective setting screens. (Factory-set items and items already set by equipment manufacturers need not be set here.)

- (1) Checking Wiring
- : Check that the wiring to connected terminals is carried out properly. If the power line is erroneously connected to other terminals, it may cause burnout.
- (2) Applying power
- : Apply operating power. The controller is energized and the data display and other lamps light.
- (3) Setting Measuring Range
 - : Select a code from the list of measuring range codes on the 5-5 Measuring range code setting screen. For current, voltage or mV input, lower/higher limit values and the position of decimal point of the contents of display in response to input signal should be set.
 - (Depending on a selected code, selection on the 5-6, 5-7 and 5-8 is also required.)
- (4) Setting Control Mode : In the case of ON-OFF (two-position) action, call the 4-1 Output proportional band setting screen of screen group 4 and select OFF for P and register it.
- (5) Setting Control Output Characteristic
 - : On the 5-12 Control output characteristics setting screen, select either RA (heating action) or DA (cooling action) for Act according to the purpose of use and register it.
- (6) Setting Other Data : Input necessary items such as program, event action and external input of program control. Record necessary data in "8. Record of Parameter Setting" and input them.
- (7) Note on Initialization upon Change of Data
 - : When a set data on measuring range code, input unit, higher/lower limit value of input scaling, event type, analog output type or the like is changed, related data is initialized and resetting is required.

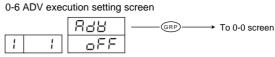


the 0-0 basic screen is returned.

In case |-| | d is set for external control input (DI), it functions only as an input status monitoring screen. ADV input is not valid during the execution of HLD.

To 0-6 screen

(2) Setting ADV Execution



Initial value: OFF 0

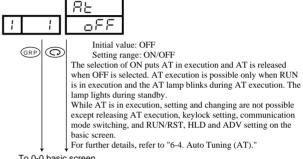
Setting range: ON/OFF
The selection of ON puts ADV in execution. Upon execution of ADV, the step currently in execution is terminated and forced to move to the next step.

This screen is displayed only when RUN is in execution in the PROG mode. If stop (RST) is input through external control input (DI) 1 or in the case of a change to FIX mode through DI, the 0-0 basic screen is returned

In case \(\frac{1}{12} \) \(\frac{1}{12} \) is set for external control input (DI), it functions only as an input status monitoring screen. ADV is not valid for 1 second upon changing to a new step and for 2 seconds upon execution of ADV

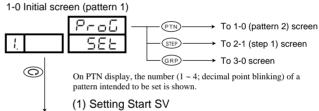
(3) Setting Auto Tuning (AT) Execution

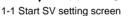
0-7 AT execution setting screen

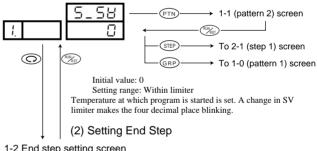


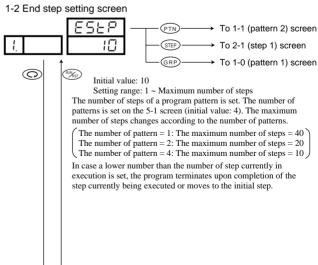
To 0-0 basic screen

5-6. Explanation of Screen Group 1 and Setting





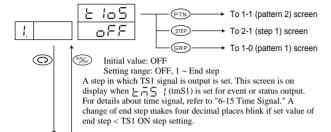




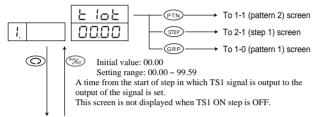
To 1-3 screen

(3) Setting Time Signal

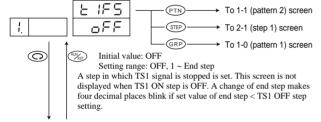
1-3 Time signal 1 (TS1) ON step setting screen



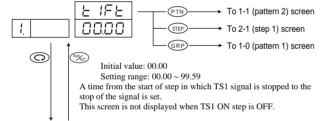
1-4 Time signal 1 (TS1) ON time setting screen



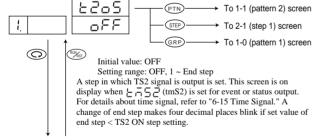
1-5 Time signal 1 (TS1) OFF step setting screen



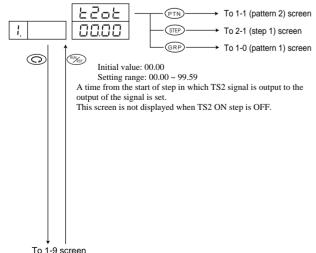
1-6 Time signal 1 (TS1) OFF time setting screen



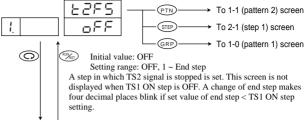
1-7 Time signal 2 (TS2) ON step setting screen



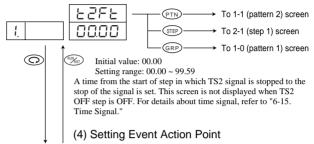
1-8 Time signal 2 (TS2) ON time setting screen



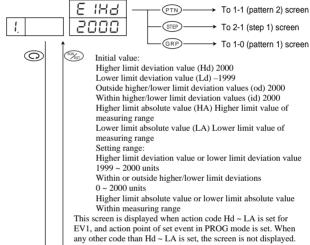
1-9 Time signal 2 (TS2) OFF step setting screen



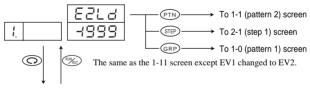
1-10 Time signal 2 (TS2) OFF time setting screen



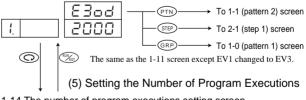
1-11 Event 1 (EV1) action point setting screen



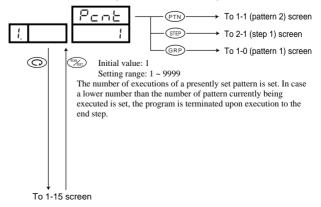
1-12 Event 2 (EV2) action point setting screen



1-13 Event 3 (EV3) action point setting screen



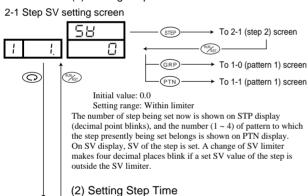
1-14 The number of program executions setting screen



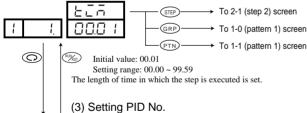
(6) Setting PV Start 1-15 PV start setting screen (PTN) → To 1-1 (pattern 2) screen -(STEP) → To 2-1 (step 1) screen → To 1-0 (pattern 1) screen 0 Initial value: OFI Setting range: ON/OFF Wasteful time is eliminated in case PV value is closer to the setting point of step 1 than start SV (7) Setting Guarantee Soak Zone 1-16 Guarantee soak zone setting screen SURE (PTN)-→ To 1-1 (pattern 2) screen oFF → To 2-1 (step 1) screen → To 1-0 (pattern 1) screen (C) Initial value: OFF Setting range: OFF, 1 ~ 999 units In case a deviation of step SV of level step from PV remains outside a guarantee soak zone when a ramp step is changed to a level step in the PROG mode, the step does not move to the next but waits until it reaches the zone. A value is set as deviation of the level step from SV. The GUA lamp lights during guarantee To 1-0 Initial screen (pattern 1)

5-7. Explanation of Screen Group 2 and Setting

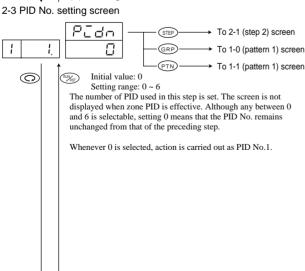
(1) Setting Step SV



2-2 Step time setting screen

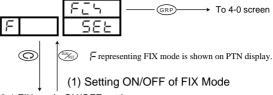


To 2-1 screen

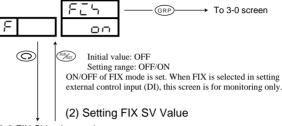


5-8. Explanation of Screen Group 3 and Setting

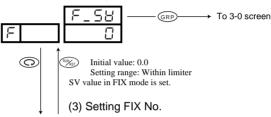
3-0 Initial screen

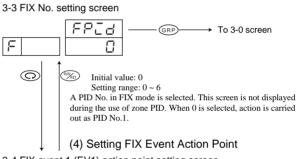


3-1 FIX mode ON/OFF setting screen

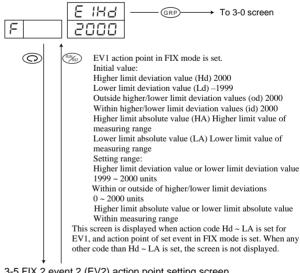


3-2 FIX SV value setting screen

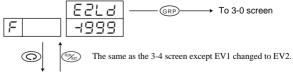




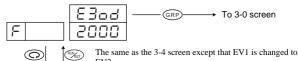
3-4 FIX event 1 (EV1) action point setting screen



3-5 FIX 2 event 2 (EV2) action point setting screen



3-6 FIX event 3 (EV3) action point setting screen

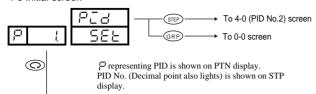


EV3 To 3-0 initial screen

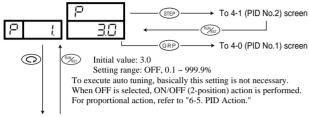
5-9. Explanation of Screen Group 4 and Setting Setting of PID Nos.1-6

(1) Setting Outputs of PID Nos. 1~6

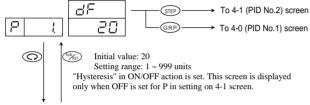
4-0 Initial screen



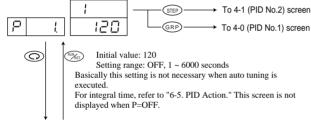
4-1 Output proportional band setting screen



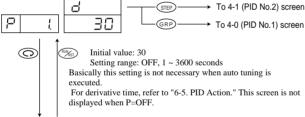
4-2 Output hysteresis setting screen



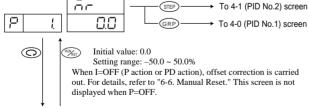
4-3 Output integral time setting screen



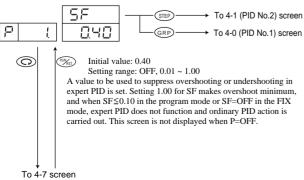
4-4 Output derivative time setting screen



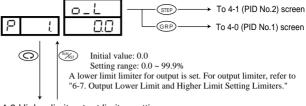
4-5 Output manual reset setting screen



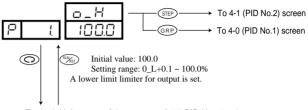
4-6 Output target value function setting screen



4-7 Lower limit output limiter setting screen



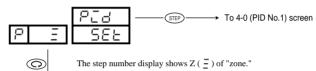
4-8 Higher limit output limiter setting screen



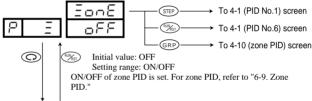
To the initial screen of the set one of 4-0 PID Nos.1 ~ 6.

(2) Setting Zone PID

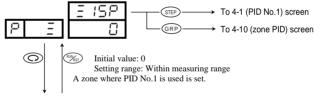
4-10 Initial screen



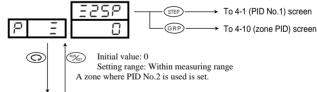
4-11 Zone PID ON/OFF setting screen



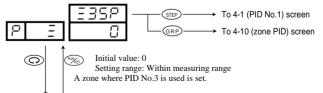
4-12 Zone 1 SP setting screen



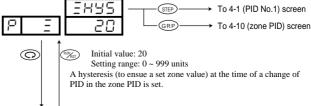
4-13 Zone 2 SP setting screen



4-14 Zone 3 SP setting screen



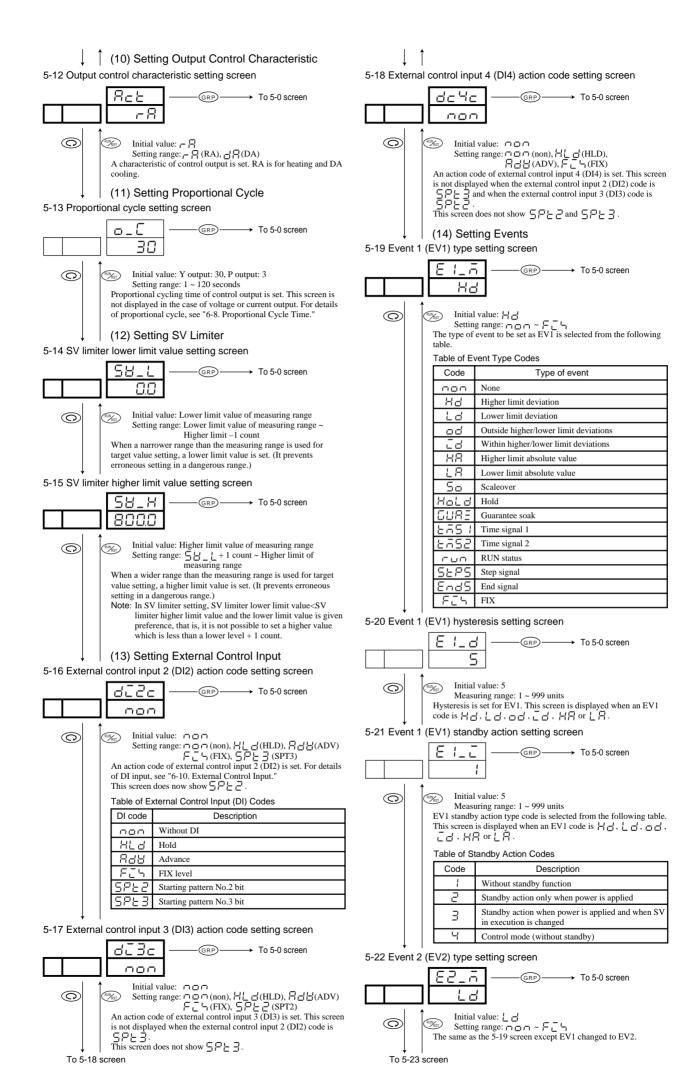
4-15 Zone hysteresis setting screen

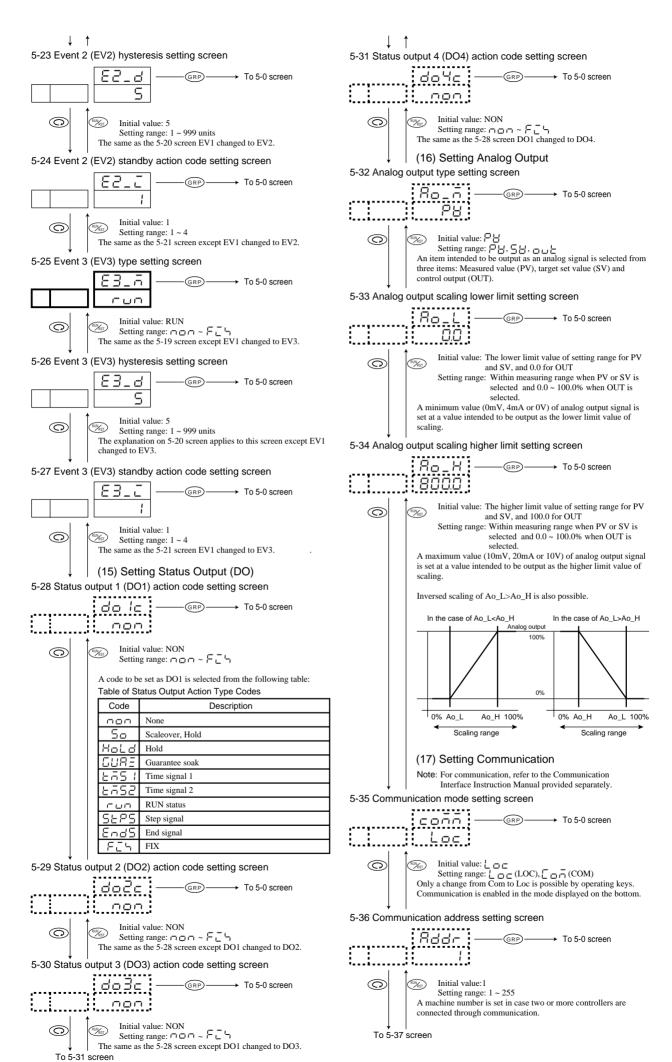


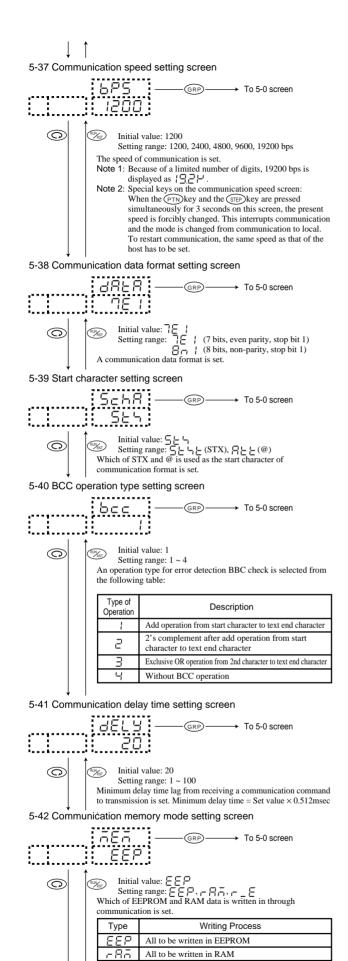
To 4-10 Initial screen of zone PID.

5-10. Explanation of Screen Group 5 and Setting (5) Setting Measuring Range Code 5-5 Measuring range code setting screen 5-0 Initial screen -8-5 — GRP → To 5-0 screen → To 0-0 screen GRP) 85 0 In this screen group, nothing is shown on the PTN and STP Initial value: 05 0 Setting range: 01 ~ 92 A measuring range is set. A table of measuring range codes is shown in "5-11. Measuring Range Code Table." A set code is unable to be changed during RUN in the PROG mode. (1) Setting the Number of Patterns 5-1 The number of patterns setting screen (6) Setting Input Unit → To 5-0 screen 5-6 Screen for changing set input unit Unite GRP)— → To 5-0 screen (C) RUN Initial value: 4 Setting range: 1, 2, 4 The number of patters to be used is set. Maximum steps of a Initial value: ☐ Setting range: ☐ / ☐ 0 pattern changes according to the number of patterns: 40 steps when the number of patterns is 1, 20 when it is 2 and 10 when it is The unit for sensor input display is selected between \sqsubset (°C) and \vdash (°F). The screen is not displayed when linear input (mV, V, A set number is unable to be changed during RUN in the mA) is selected. A set unit is unable to be changed during RUN in PROG mode (2) Setting Time Unit (7) Setting Input Scaling 5-2 Time unit setting screen 5-7 Input scaling lower limit value setting screen ŁĀUn -GRP)-→ To 5-0 screen —(GRP) → To 5-0 screen 0.0 (C) Initial value: ├ ┌ ┌ Kan Initial value: ├ ┌ ┌ Kan Initial value: ├ ┌ ┌ (HM)/ ┌ ┌ (MS) A unit of time used in various items, such as step signal and step 0 Initial value: 0.0 Setting range: –1999 ~ 9989 units A lower limit value of scaling for linear input (mV, V, mA) is set. Hime, is set. Himstands for "~hours~minutes" and Time is set. Himstands for "~hours~minutes" and Time is set. A set unit is unable to be changed during RUN in the PROG During sensor input, the lower limit of measuring range is displayed and no change is possible. A set value is unable to be changed during RUN in the PROG mode. 5-8 Input scaling higher limit value setting screen H (3) Setting With/Without Power Failure Compensation 56. -GRP → To 5-0 screen 5-3 With/without power failure compensation setting screen 1000 SARE -GRP)-→ To 5-0 screen Initial value: 100.0 0 Setting range: (Input scale) lower limit value + 10 ~ Lower oFF limit value + 5000 units A higher limit value of scaling for linear input (mV, V, mA) is A ligher limit value of scanning for limear input (lifty, v, lin/) is set. During sensor input, the higher limit of measuring range is displayed and no change is possible. A set value is unable to be changed during RUN in the PROG mode. Note: If a lower limit value is set so as to have a difference of less (C) Initial value: OFF Setting range: ON/OFF When OFF is set, the instrument starts up in the state of RST in the PROG mode when power is applied again, that is, a state preceding the power failure is not maintained. When ON is selected, the instrument starts up in a state preceding the power than 10 counts or more than 5000 counts from a higher limit value, the higher limit value is forcibly changed to the lower limit value +10 counts or the lower limit value +5000. failure. (In the FIX mode, a state preceding the power failure is always maintained.) 5-9 Input scaling decimal point position setting The following are excluded, however: AT in execution. ScdP GRP)-→ To 5-0 screen A change in the state of DI input (Power supply is interrupted in the state of ON, turned OFF during interruption). PID No. where hysteresis of zone PID is involved. Initial value: 0.0 (4) Setting Input Abnormality Mode 0 Setting range: Without decimal point (0) ~ 3 decimal 5-4 Input abnormality mode setting screen places (0.000) The position of decimal point for input scaling is set. During 55 sensor input, the screen is for monitoring only and no setting is possible. A set position is unable to be changed during RUN in HLthe PROG mode Initial value: HLd Setting range: HLd (HLD), run(RUN), r5t (RST) How to deal with sensor break or scaleover, which may occur in the process of program control, is set. 0 (8) Setting PV Bias 5-10 PV Bias setting screen Ь -GRP To 5-0 screen 片는 급: The HLD state precedes recovery from scaleover or resetting. Output is fixed to 0%. If the sensor has no problem, the HLD state is released upon applying power Initial value: 0.0 ாட்டா: Program action continues until the program ends or reset 0 Setting range: -1999 ~ 2000 units is input. (Time continuation) Output is fixed to 0%. — 5 \(\): Program action is released and the instrument is put in PV bias is used to correct an error of input from sensor or the like. When a bias is set, control is also carried out with a corrected value. the state of reset. (9) Setting PV Filter 5-11 PV filter setting screen F -GRP-→ To 5-0 screen Setting range: 0 ~ 100 seconds In case input changes conspicuously or noise continues, PV filter is used to mitigate such undesirable effect. When 0 second is set, To 5-5 screen filter does not function

To 5-12 screen

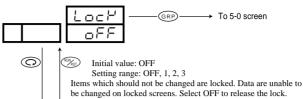






1 (18) Setting Keylock

5-43 Keylock setting screen



To 5-0 Initial screen

Lock No.	Range to be locked
oFF	Release of lock (All data allowed to be changed.)
1	Keylock of the screen groups 3, 4 and 5 (excluding communication mode and special keys on communication speed screen)
2	Keylock of screen groups 1, 2, 3, 4 and 5 (excluding communication mode and special keys on communication speed screen)
3	Keylock of all screens excluding RUN/RST on the basic screen, communi- cation mode screen and special keys on communication speed screen)

5-11. Measuring Range Codes Table

Select a measuring range from the following table.

Note: A change of a measuring range code will initialize all data related to the measuring range.

			ig runge.	Measuri	ng range
Input type		Code	ßC	ßF	
		B *1	0 1	0 ~ 1800	0 ~ 3300
		R	02	0 ~ 1700	0 ~ 3100
		S	03	0 ~ 1700	0 ~ 3100
			[] Ч∗₂	-199.9 ~ 400.0	-300 ~ 750
		K	85	0.0 ~ 800.0	0 ~ 1500
	ıple		08	0 ~ 1200	0 ~ 2200
	Thermocouple	Е	07	0 ~ 700	0 ~ 1300
	nerm	J	80	0 ~ 600	0 ~1100
	П	T	3 9*2	-199.9 ~ 200.0	-300 ~ 400
		N	10	0 ~ 1300	0 ~ 2300
		PLII *3	1.1	0 ~ 1300	0 ~ 2300
		Wre5-26*4	12	0 ~ 2300	0 ~4200
		U *5	1∃*2	-199.9 ~ 200.0	-300 ~ 400
		L *5	14	0 ~ 600	0 ~1100
Ħ			3 :	-200 ~ 600	−300 ~ 1100
-inp		Pt	32	-100.0 ~ 100.0	-150.0 ~ 200.0
Multi-input			33	-50.0 ~ 50.0	−50.0 ~ 120.0
~	R.T.D.		34	0.0 ~ 200.0	0.0 ~ 400.0
	R.7	JPt	35	-200 ~ 500	-300 ~ 1000
			38	-100.0 ~ 100.0	-150.0 ~ 200.0
			37	-50.0 ~ 50.0	-50.0 ~ 120.0
			38	0.0 ~ 200.0	0.0 ~ 400.0
		-10~10mV	71		
		0~10mV	72		
	mV	0~20mV	73		
	п	0~50mV	74		
		10~50mV	75	Scaling possible.	
		0~100mV	75	Setting range: —1999	~ 9999
		-1~1V	8 !	Span: 10 ~ 5000	
		0~1V	82	-	. 0 000 N
	>	0~2V	83	Decimal point position	: 0.000 ~ None
		0~5V	84		
		1~5V	85		
		0~10V	88		
m	A	0~20mA	<u> 9 !</u>		
		4~20mA	92		

Thermocouple B, R, S, K, E, J, T, N: JIS/IEC R.T.D Pt100: JIS/IEC; JPt100: Former JIS

- R.1.D PHOU: IB/IBC; JPHOU: Former JIS

 *1 Thermocouple B. Accuracy guarantee not applicable to 400BC(725BF) and below.

 *2 Thermocouple K, T, U: Accuracy of those whose readings are below —100BC is ±0.7% FS.

 *3 Thermocouple PLII: Platinel

 *4 Thermocouple Were5-26: A product of Hoskins

 *5 Thermocouple U, L: DIN 43710

 ◆ When not designated, factory-set measuring range is K thermocouple (0.0 ~ 800.0BC).

FIX SV, OUT and STEP SV to be written in RAM

and others in EEPROM

Communication Memory Mode.

* Note on the RAM mode selected as communication mode:

Since all are written in RAM, setting inconsistency may arise in some case. For details, refer to "6-17. Notes on RAM as

-18

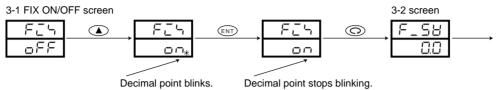
To 5-43 screen

6. Operation and Functions

6-1. Using FIX Mode

FIX: Adjustment function without using the program function.

- ① Pressing the or vert key on the 3-1 FIX ON/OFF screen turns OFF shown on the target value (SV) display to ON and the decimal point of the rightmost digit blinks. Then, press the vert key, and the decimal point stops blinking to register the selection. (When OFF is set for FIX on this screen, the program mode turns ON.)
- 2 Pressing the key calls the next setting screen. Set a necessary item, if any.
- 3 When the display returns to the basic screen upon completion of setting, F is shown on the pattern number display and the FIX mode is ON.



6-2. Setting Target Value (SV) (FIX Mode)

① Setting on the basic screen

When the
or the value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the keys is to register it. The registration of the data stops the blink of the decimal point.

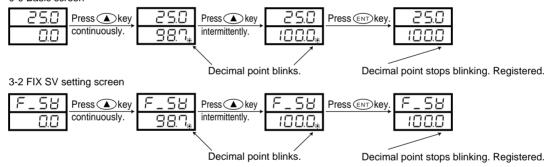
② Setting on the SV setting screen

When the
or the
key is pressed on the 3-2 FIX SV setting screen, the decimal point of the rightmost digit blinks and the numerical value changes. The value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the key to register it. The registration of the data stops the blink of the decimal point.

- * In the program mode, SV value is unable to be changed on the basic screen.
- * In the program mode, the 1-1 start SV setting screen and the 2-1 step SV setting screen should be used to set an SV.
- * No target value can be changed while auto tuning (AT) is in execution. It should be set after releasing AT.

Example: Setting target value at 100°C





6-3. Setting Output Manually

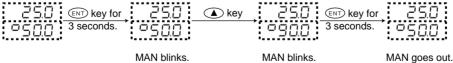
For switching between auto and manual, press the (ENT) key continuously for 3 seconds (in the state of RUN) on the output monitoring screen.

During manual output, the MAN lamp lights and it goes out when automatic output begins.

To set a target value, press the or key on the output monitoring screen. When the target value is reached, the setting completes. To release it, press the setting key again for 3 seconds continuously, and automatic output is resumed.

- * Changing to manual output is not possible while auto tuning is in execution.
- ① 100% output is shown as $\boxed{.339}$ and the decimal point of $\boxed{.}$ blinks.
- 2 When OFF is set for proportional band (P) in the case of contact output or SSR drive voltage output, the value of output is either 0.0% or 100.0%.
- ③ When OFF is set for proportional band (P) in the case of voltage output or current output, the output value becomes the lower or higher limit value of a set output limiter.

0-1 Output monitoring screen



- 4 Supplementary Explanation of Monitoring Screen
 - The output monitoring screen (OUT) and automatic output/manual output:
- 1) When auto is changed to manual, output is in balanceless action and an output value immediately before the change is displayed.
 - When manual is changed to auto, output is in bumpless action if it is bumpless. If it is outside the proportional band, however, the output is not in bumpless action.
- 2) In case power supply was turned OFF and power is applied again, control output is in the mode (either manual or auto) which was ON at the time of interruption of power supply.

NOTE: Even in the manual mode, it is possible to call another screen but it should be noted that control output is in the manual state. Blinking of the MAN action LED shows that the manual mode is ON.

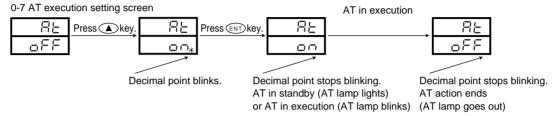
6.4. Auto Tuning (AT)

This is the function to automatically calculate and set P.I.D. values, i.e., parameters of PID control. The time required for calculation depends on the details of control.

① Execution of AT

Pressing the AT execution setting screen changes OFF shown on the target set value (SV) display to ON and the decimal point on the rightmost digit blinks. Upon pressing the key, the decimal point stops blinking and AT action begins. When the target set value stays in the inclined portions (portions indicated by the arrows of the action display), AT is in the state of standby (the AT lamp lights), and AT is executed while the target set value stays in the level portion (the AT lamp blinks).

While AT is in execution, the ON/OFF action of output is repeated several times in accordance with rise and fall of the measured value from the target value as the border and PID values are stored in an internal memory. Immediately when they are stored, control using these PID values begins and AT action ends. Then, the target set value display shows OFF and the AT lamp goes out. (In case there is AT still to be executed, it is put in the state of standby.)



② Release of AT in the Middle

To release AT in the middle, select OFF on the AT execution setting screen by the use of very key and press the key.

NOTE: In case AT is released in the middle, PID values are not changed.

- 3 Reasons Why AT Does Not Function
- 1) Control output is in manual mode.
- 2) The proportional band (P) of control output is OFF.
- 3) PV value (measured value) is in the state of scaleover.
- 4) On the keylock screen, No. 3 is selected. (AT is executed when it is turned ON before keylock setting.)
- 5) AT is suspended (RST).
- 4 If the following conditions arise while AT is in execution, AT is released:
- 1) Output is at 0% or 100% continuously for 200 minutes.
- 2) PV value gets scaleover.
- 3) RST input is received.
- 4) AT is terminated by key operation or through communication.
- 5) AT of PID No. 1 through No. 6 (No. 3 in the case of zone) has completed.

6-5. PID Action

① P (Proportional action)

The ratio (%) of a range in which control output changes relatively to a measuring range is set. Output increases or decreases in proportion to difference between PV value and SV value. The narrower the proportional band, the larger a change in output, i.e., the stronger the proportional action. Nonetheless, an excessively narrow proportional band causes control to vibrate, resulting in control similar to ON-OFF action.

② I (Integral time)

This is the function to correct an offset (constant deviation) produced in proportional band. The longer the integral time, the weaker the correcting action, that is, reducing the integral time strengthens the correcting action but it may cause undulation of control results due to integral hunting.

③ D (Derivative time)

A change in control output is estimated and overshooting is suppressed to improve the stability of control. A longer derivative time strengthens derivative action but it may cause control results to vibrate.

6-6. Manual Reset

In PID action, an offset is corrected automatically by I, i.e., integration. When OFF is set for I, however, this correction is not carried out and so output is increased or decreased manually for correction. This method is called manual reset.

6-7. Output Lower Limit and Higher Limit Setting Limiters

- ① Output limiter means to limit a minimum or maximum value of control output and this function is effective in securing the lowest temperature or suppressing overshooting of control.
- ② Output limiter gives preference to a lower limit value. When a larger lower limit value than a higher limit value is set, the higher limit value is forced to become the lower limit value +0.1%. In other words, it is not possible to set a higher limit value which is less than a lower limit +0.1%.

6-8. Proportional Cycle Time

It can be set within a range from 1 to 120 seconds in the case of contact output or SSR drive voltage output. Proportional cycle time is ON time + OFF time within a proportional band.

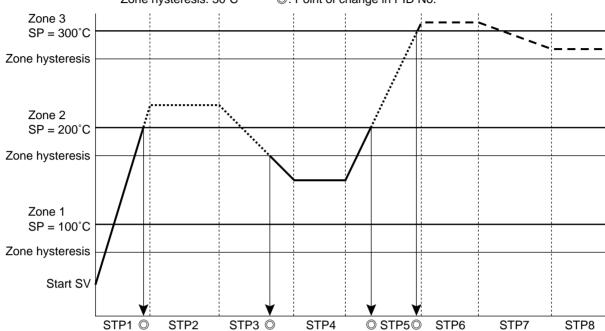
6-9. Zone PID

The PID control of this instrument allows you to select and set the zone method.

In the zone PID control, a measuring range is divided into three types maximum, and control is carried out with PID No. which is selected automatically from an SV value set for each step.

Its basic action is: PID No. changes when control output becomes larger than an SP value or smaller than a zone hysteresis. An example of its action is diagramed below.





When above diagram shows SV as: Below $200^{\circ}\text{C} \rightarrow \text{Action with PID No. 1}$

 $200^{\circ}\text{C} \sim 300^{\circ}\text{C} \rightarrow \text{Action with PID No. 2}$

Above $300^{\circ}\text{C} \rightarrow \text{Action with PID No. } 3$

When the setting of zone SP is changed as follows:

Zone 3 SP: 100° C Below 200° C \rightarrow Action with PID No. 3

Zone 1 SP: 200°C ~ 300 °C \rightarrow Action with PID No. 1 Zone 2 SP: 300°C Above 300°C \rightarrow Action with PID No. 2

6-10. External Control Input (DI)

The instrument has four DIs. DI is caused to function when any other item than non is set on the setting screen and external terminals are shorted. Action caused by each setting is described below:

① RUN/RS7

Switching between RUN and RST. As this is assigned to DI1 fixedly, the setting is unable to be changed. Being edge input, RUN and RST are switched by shorting across terminals 1 and 2.

② ADV

As on the 0-6 ADV execution screen, when executed, the present step comes to an end and is forced to proceed to the next step. Being edge input, ADV is executed every shorting across terminals.

3 HLD

As on the 0-5 HLD execution screen, when executed, the present step time is temporarily suspended and SV is fixed. Being level input, shorting across terminal puts HLD in execution and opening releases it. A change in step time, step SV, time signal ON/OFF time, etc. does not take effect until HLD is released.

4 FIX

As on the 3-1 FIX mode ON/OFF setting screen, when executed, the FIX mode turns ON. Being level input, shorting across terminals turns the FIX mode ON and opening releases it.

⑤ SPT3

A pattern No. at the start of program action is selected by 3 bits of DI2~DI4.

6 SPT2

A pattern No. at the start of program action is selected by 2 bits of DI3 and DI4. Being level input, shorting across terminals produces "1" and opening "0". Since the time for removing chattering of level input is 125msec, edge input action need to remain ON for 125msec or longer. If a number exceeding the number of patterns is input, a maximum number of patterns allowed to be set can be set.

For example: Where the number of patterns = 2 and DI input is 011, the number of start pattern is 2.

	DI4,	3,	2		DI4, 3	
s	0	0	0	Start with pattern 1	0 0	s
_	0	0	1	Start with pattern 1	0 1	_
Р	0	1	0	Start with pattern 2	1 0	Р
Т	0	1	1	Start with pattern 3	1 1	т
	1	0	0	Start with pattern 4	Not possible	•
3	1	0	1	Start with pattern 4	Not possible	2
	1	1	1	Start with pattern 4	Not possible	

^{*} When the same zone SP value is set, the lowest number is used preferentially.

^{*} Even when a zone SP value in action is changed within a zone hysteresis, PID No. is not changed as long as output remains within the hysteresis.

6-11. Events

1 Deviation Alarm

An alarm action point is set by a deviation of measured value (PV) from target set value (SV). For instance, to activate an alarm when measured value (PV) reaches 30° C against SV value at 20° C, higher limit deviation alarm is set at 10° C. To activate alarm when measured value (PV) lowers below 30° C in the case of an SV value at 100° C, lower limit deviation alarm is set at -70° C. This function is convenient for an alarm action point to follow deviations from target set value. The set range is $-1999 \sim 2000$ units.

② Absolute Value Alarm

An alarm point is set by an absolute value.

For instance, to activate an alarm when measured value exceeds 50°C, higher absolute value alarm is set at 50°C. To activate an alarm when measured value lowers below 20°C, lower absolute value alarm is set at 20°C. Setting of higher or lower absolute value alarm is possible as long as it is within the measuring range.

3 Standby Action

In case 2 or 3 is set for event standby action, there is no event output upon applying power (or changing target set value) even when measured value is within an event action area (an ON area). Event is output when it reaches the event action area again after it gets out of the event action area (gets in an OFF area).

4 Non-standby Action

In case event standby action is set for 1 and 4, an alarm is output when measured value gets in an action area upon applying power (or changing target set value).

⑤ Control Mode (4 is set for standby action)

No event is output at the time of scaleover. The same applies to event standby.

6-12. Setting Event Standby Action

On 5-21 Event 1 standby action code setting screen

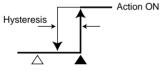
- ① When event output is used as an alarm, select from 1, 2 and 3 of the standby action code table.
- ② When event output is used for control, set 4 (control mode). In case 4 is selected, however, event output turns OFF at the time of input abnormality.
- ③ When 2 is selected, standby action functions only when power is applied.
- ④ When 3 is selected, standby action functions when power is applied and when SV in execution is changed.
- (§) When changed to 1 or 4 while standby action is going on, the standby action is released immediately.
- © Even when 2 or 3 is selected as standby action, it has no effect if PV value is outside the ON area of event action when power is applied or SV is changed.

6-13. Diagrams of Alarm Actions Selectable as Event

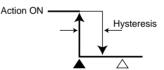
Diagrams of alarm actions to be selected for event 1~3 are shown below:

∴ : SV value
 ∴ : Set value of alarm action point

님님: Higher limit deviation alarm



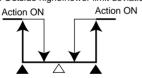
Ĺ 占 : Lower limit deviation alarm



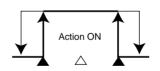
서류: Higher limit absolute value alarm



ு ு : Outside higher/lower limit deviations alarm



교 : Inside higher/lower limit deviations alarm



 $\c \Box$: Lower limit absolute value alarm



6-14. Event and Status Output Actions

The following nine items can be set for status output of "5-28, 5-29, 5-30 and 5-31" as well as events:

THE TOIL	owing innerier	ils call be set for status output of 3-26, 3	1-29, 3-30 and 3-31	as well as events.
So	Scaleover	: To be output when measured value	Action ON	Action ON
		(PV) gets 10% above or below		
		higher/lower limits of measuring	T	Τ
		range.		\wedge
		(See the diagram on the right.)	_10% ←—PV	✓ value → 110%

HoL : To be output while HLD is set on DI input and 0-5 HLD execution setting and in communication

in the PROG mode.

Guarantee soak: To be output while the state of guarantee remains in the PROG mode.

 $\pm \overline{5}$; Time signal 1: To be output in the ON/OFF condition set in the time signal 1 setting (1-3, 1-4, 1-5 and 1-6) in the

PROG mode. For details, see 6-15.

 $\exists \exists \exists$ Time signal 2 : To be output in the ON/OFF condition set in the time signal 2 setting (1-7, 1-8, 1-9 and 1-10) in

the PROG mode. For details, see 6-15.

านา RUN status : To be output while RUN action is in execution.

 ${\tt 5} {\tt LPS} \quad \text{Step signal} \qquad : \text{To be output for one second when a step proceeds to another in the PROG mode}.$

 $\exists \neg \exists \subseteq \exists$ End signal : To be output for one second when the last step ends in the PROG mode.

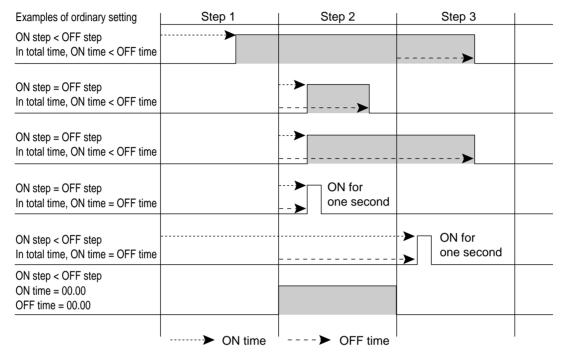
F = FIX : To be output while RUN action is in execution in the FIX mode.

6-15. Time Signal

Time signal: Event output and status output can be produced for a designated period of time. Two points per pattern are equipped and ON step, OFF step, ON time and OFF time can be set individually.

- ① Time signal functions under the following conditions:
- 2) OFF is not selected in Time signal ON step setting.
- 3) ON time is set within the end step.
- 4) In the total length of time elapsed since the start of program, ON time \leq OFF time.
 - In the case of ON step = OFF step and ON time = OFF time, time signal turns ON for one second.
 - In the case of ON step < OFF step and ON time = OFF time in the total length of time elapsed since the start of program, time signal turns ON for one second.

(Example of setting: 1 step 10 minutes, ON step = 1, ON time 15 minutes, OFF step = 2 and OFF time 5 minutes)



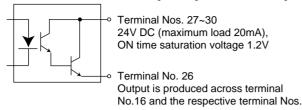
- * When a time signal-related parameter is changed during Hold (HLD), the change is not reflected until HLD is released.
- ② Reasons why time signal does not function (always OFF) (Time signal does not function in the following cases):
- 1) $\xi \pi \xi$ for $\xi \pi \xi \xi$ is not set as status output of event output (including the case where these options are not added).
- 2) OFF is selected as Time signal ON step setting.
- 3) ON time exceeds the end step.
- 4) In the total length of time elapsed since the start of program, ON time > OFF time is set.
- 3 Other Matters related to Setting
- 1) The time of time signal is stopped during HLD and guarantee soak.
- 2) In case ON step and ON time are set and OFF step is OFF, once time signal turns ON, the end step also turns ON. (When one or more program executions are set, both remain ON until they are completed.)
- 3) In case OFF time is set beyond the end step, the end step is forcibly turned OFF. When ON step is the first step and 00:00 is set for ON time, it does not turn OFF.
- 4) In case ON time equals step time, it turns ON at the start of the next step.

Other examples of setting	Step 1	Step 2	Step 3	
ON time > end step (time signal not effective)				···· >
ON step = OFF only ON step is effective (remains ON until the program completes.)		>		
OFF time > end step (forcibly turned OFF at the end step.)				>
	ON time	➤ OFF time		

5) When TS is assigned to a step of which the step time is 0, the action is the same as TS is assigned to the next step.

6-16. Status (DO) Output

This instrument has four status output as optional function (open collector output) points.



6-17. Auto Return Function

Should there be no key operation for 3 minutes on each screen except the monitoring screens (adjustment output, remaining time of step, the number of pattern executions, PID No.), the display returns automatically to the 0-0 basic screen of screen group 0 (auto return).

6-18. Notes on RAM as Communication Memory Mode

In case RAM is selected on the 5-42 communication memory mode, all set data are written in RAM. Care should be taken as this causes nonconformity of set data in a pattern like the following:

On the assumption that input range is 05 (K 0.0~800.0°C),

- ① An event code is changed from higher limit deviation value to higher limit absolute value through communication (this change is recorded in RAM).
- ② Communication mode is changed from COM to LOC.
- ③ Event action point setting is changed from 800.0 to 700.0 by key operation. (Being in LOC mode, this change is recorded in EEPROM).
- ④ Power supply is interrupted and power is applied again.
- (§) The event code recorded in RAM is cleared and higher limit deviation value is read from EEPROM.
- 6 Since the event action point set as 700.0 has been written in EEPROM, 700.0 is read.
- ② Consequently, although the setting range of higher limit deviation value is actually -1999~2000 units, an impossible value of 7000 units is set.

To ensure proper use of the instrument, correct data must be set again.

7. Error Codes, Causes and Remedies

Screen display	Problem	Cause	Remedy
片片片 (HHHH)	Higher limit side scaleover	Break of thermocouple input wiring Break of R.T.D. input A wiring Input measured value exceeded higher limit of measuring range by more than 10%.	Check thermocouple input wiring. If wiring has no problem, check and replace thermocouple. Check wire connection to R.T.D. terminal A. If wiring has no problem, replace R.T.D. For voltage or current input, check the transmitting unit of measured values. Check if set code of measuring range is the same as that of input signal.
LLLL (LLLL)	Lower limit side scaleover	Problem with wiring connection for input signal Input measured value fell from lower limit of measuring range by 10% Nonconformity of input range with input signal	Check wire connection for input signal. Check wiring of inversed polarity or break of wiring for measured value input. Check input range and input signal.
(b)	Break of R.T.D. input wiring	① Break of B ② More than one break of A, B and B	Check R.T.D. input terminals A, A and B for breaks. If wiring has no problem, check and replace R.T.D.
(CJHH)	Higher limit side scaleover of cold junction (CJ) of thermocouple input	Ambient temperature of FP93 has exceeded 80°C.	Reduce ambient temperature to the level provided in the environment conditions. In case ambient temperature has not exceeded 80°C, examine the instrument.
[_JL L	Lower limit side scaleover of cold junction (CJ) of thermocouple input	Ambient temperature of instrument has fallen to -20°C or lower.	Raise ambient temperature to the level provided in the environment conditions. In case ambient temperature has not fallen to -20°C, examine the instrument.

Note: When you find something wrong with the instrument, please re-read the instruction manual and examine the instrument again. For any problem with the product or further information, please contact our sales agent.

8. Record of Parameter Setting

(For convenience sake, recording set values and selected items is recommended.) The initial values are of Code 05 (K).

Screen No.	Parameter (Item	n)/Screen	ı	Initial value	Setting/Selection	Remarks
0-0	Basic screen	0	([])	0		
0-1	Output monitor					
0-2	Step remaining time					
0-3	Pattern execution number monitor					
0-4	PID No. monitor					
0-5	HLD execution setting	HLd.	(HLB)	oFF		
0-6	ADV execution setting	AdV.	(898)	oFF		
0-7	AT execution setting	At.	(AE)	oFF		
				_		
1-0	Initial screen	ProG.	(Pro5)	588		
1-1	Start SV	S_SV.	(5_58)			
1-2	End step	EStP.	(ESEP)	10		
1-3	TS1 ON step assignment	t1oS.	(E 105)	oFF		
1-4	TS1 ON time	t1ot.	(E 10E)	00.00		
1-5	TS1 OFF step assignment	t1FS.	(E :F5)	oFF		
1-6	TS1 OFF time	t1Ft.	(E 1FE)	00.00		
1-7	TS2 ON step assignment	t2oS.	(E2o5)	oFF		
1-8	TS2 ON time	t2ot.	(E2oE)	00.00		
1-9	TS2 OFF step assignment	t2FS.	(E2F5)	oFF		
1-10	TS2 OFF time	t2Ft.	(E2FE)	00.00		
1-11	EV1 level value	E1**.	(E ; * *)	Hd: 2000unit		
	***includes action type.		(= . /	Ld: -1999unit		
1-12	EV2 level value	E2**.	(E2 * *)	od: 2000unit id: 2000unit		
	★**includes action type.		(/	HA: Higher limit of		
1-13	EV3 level value	E3**.	(E3 * *)	measuring range		
	★**includes action type.		(23 /	LA: Lower limit of measuring range		
1-14	Pattern execution number	Pcnt.	(Pcnt)	!		
1-15	PV start	PV_S.	(PB_5)	off		
1-16	Guarantee soak zone	GUAZ.	(GURE)	off		
			(002)	<u> </u>		
2-1	Step SV	SV.	(58)	0		
2-2	Step time	tim.	(F <u>[</u> 22]	00.0 1		
2-3	PID No.	Pidn.	(Pidn)	0		
			(, , , ,			
3-0	Initial screen	FiX.	(Fこち)	SEŁ		
3-1	FIX ON/OFF	FiX.	(F_5)	oFF		
3-2	FIX SV value setting	F_SV.	(F_58)	0		
3-3	FIX PID No. setting	FPid.	(FPZd)	0		
3-4	EV1 level value	E1**.	(E : * *)	Hd: 2000unit		
	★**includes action type.		/	Ld: -1999unit		
3-5	EV2 level value	E2**.	(82 * *)	od: 2000unit id: 2000unit		
	★**includes action type.		/	HA: Higher limit of		
3-6	EV3 level value	E3**.	(E3 * *)	measuring range LA: Lower limit of		
	***includes action type.		/	measuring range		
	7.5 7/15			3 2 9		
PID No. 1	•					
4-0	Initial screen	Pid.	(P[d)	SEE		
4-1	PID P	P.	(P)	3.0		
4-2	PID hysteresis	dF.	(JF)	20unit		
4-3	PID I	I.	(;)	120		
4-4	PID D	d.	(♂)	30		
4-5	PID MR	mr.	(5-)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	o_L.	(o_L)	0.0		
4-8	PID higher limit	o_H.	(o_H)	100.0		
		_	· — — · · · /			
	ı					1

Screen No.	Parameter (Iter	n)/Screen		Initial value	Setting/Selection	Remarks
PID No. 2	`	Í				
4-0	Initial screen	Pid.	(P_d)	SEE		
4-1	PID P	P.	(P)	3.0		
4-2	PID hysteresis	dF.	(dF)	ے۔ <u>۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ ۔ </u>		
4-3	PID I					
4-3 4-4	PID D	l.	(;)	120		
	PID MR	d.	(占)	30		
4-5		mr.	(5-5)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	0_L.	(o_L)	0.0		
4-8	PID higher limit	o_H.	(o_H)	100.0		
PID No. 3	T		.==			
4-0	Initial screen	Pid.	(우급급)	585		
4-1	PID P	P.	(尸)	3.0		
4-2	PID hysteresis	dF.	(라도)	20unit		
4-3	PID I	l.	(;)	120		
4-4	PID D	d.	(급)	30		
4-5	PID MR	mr.	(5-)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	o_L.	(<u>-</u> L)	0.0		
4-8	PID higher limit	o_H.	(o_H)	100.0		
PID No. 4						
4-0	Initial screen	Pid.	(5.7.7)	588		
4-1	PID P	P.	(尸)	3.0		
4-2	PID hysteresis	dF.	(남두)	20unit		
4-3	PID I	l.	(;)	120		
4-4	PID D	d.	(급)	30		
4-5	PID MR	mr.	(5-)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	o_L.	(0_L)	0.0		
4-8	PID higher limit	o_H.	(o_H)	100.0		
PID No. 5		1	(02///	. 0 0.0		
4-0	Initial screen	Pid.	(P[d)	SEŁ		
4-1	PID P	P.	(P)	3.0		
4-2	PID hysteresis	dF.	(급위)	20unit		
4-3	PID I	I.	(;)	120		
4-4	PID D	d.	(급)	30		
4-5	PID MR	mr.	(ā-)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	o_L.		0.0		
4-7	PID lower limit	o_L. o_H.	(- ")	100.0		
4-8 PID No. 6	חיווא וופווווווו מיון די ווווווו	о_п.	(0_H)	100.0		
4-0	Initial screen	Pid.	(P[a)	,		
	PID P	P.		<u>588</u>		
4-1			(P)	3.0 30unit		
4-2	PID hysteresis	dF.	(남동)	20unit		
4-3	PID I	I.	(;)	150		
4-4	PID D	d.	(급)	30		
4-5	PID MR	mr.	(5-)	0.0		
4-6	PID SF	SF.	(SF)	0.40		
4-7	PID lower limit	o_L.	(o_L)	0.0		
4-8	PID higher limit	o_H.	(p_H)	100.0		
Zone PID						
4-10	Initial screen	Pid.	(무급성)	5E Ł		
4-11	Zone ON/OFF	ZonE.	(EonE)	6FF		
4-12	Zone 1 SP	Z1SP.	(E (SP)	Ounit		
4-13	Zone 2 SP	Z2SP.	(E25P)	0unit		
4-14	Zone 3 SP	Z3SP.	(EBSP)	0unit		
4-15	Zone hysteresis	ZHYS.	(EHY5)	20unit		

Screen No.	Parameter (Item	n)/Screen	ı	Initial value	Setting/Selection	Remarks
5-0	Initial screen	init.	(こっこと)	58Ł		
5-1	Pattern No. designation	Ptn.	(PEn)			
5-2	Time designation	tmUn.	(EāUa)	HĀ		
5-3		SAVE.	(2.9E)	oFF		
5-4	Input abnormality code	So.	(50)	HLB		
5-5	Measuring range	rAnG.	(-8-5)	05		
5-6	Input unit	Unit.	(Unit)			
5-7	Input scale lower limit value	Sc_L.	(Sc_L)	0.0		
5-8	Input scale higher limit value	Sc_L.	(Sc_H)	100.0		
5-9	· •	ScdP.				
	Input scale decimal point		(ScdP)	0.0		
5-10	PV bias	PV_b.	(P8_8)	0unit		
5-11	PV filter	PV_F.	(P8_F)			
5-12	Control characteristics	Act.	(Act)	- R		
5-13	Proportional cycle	o_C.	(0_[)	Y:30 P:3		
5-14	-	SV_L.	(S8_L)	0.0		
5-15	Higher limit value of SV setting		(58_8)	800.0		
5-16	External control input 2 code	di2c.	(8525)	000		
5-17	External control input 3 code	di3c.	(8236)	000		
5-18	External control input 4 code	di4c.	(८८५८)	поп		
5-19	EV1 action type	E1_m.	(E :_5)	Нd		
5-20	EV1 hysteresis	E1_d.	(E :_d)	5unit		
5-21	EV1 standby setting	E1_i.	(E !)	1		
5-22	EV2 action type	E2_m.	(E2_5)	Ld		
5-23	EV2 hysteresis	E2_d.	(E2_a)	5unit		
5-24	EV2 standby setting	E2_i.	(E2_2)	1		
5-25	EV3 action type	E3_m.	(E3_A)	run		
5-26	EV3 hysteresis	E3_d.	(83-9)	5unit		
5-27	EV3 standby setting	E3_i.	(E3_2)	i i		
5-28	Status output 1 code	do1c.				
5-29	· · · · · · · · · · · · · · · · · · ·		(do (c)	000		
	Status output 2 code	do2c.	(do <u>2c)</u>	000		
5-30	Status output 3 code	do3c.	(<u>do3c)</u>	000		
5-31	Status output 4 code	do4c.	(8040)	000		
5-32	Analog output type	Ao_m.	(<u>Ro_ā</u>)	<u> </u>		
5-33	Analog output scale lower limit		(8o_L)	0.0		
5-34	Analog output scale higher limit		(Ro_H)	800.0		
5-35	Communication mode	comm.	(Loc		
5-36	Communication address	Addr.	(유럽성८)	1		
5-37	Communication speed	bPS.	(625)	1200		
5-38	Communication data format	dAtA.	(98F8)	7E I		
5-39	Start character	SchA.	(Sch:)	567		
5-40	BCC operation	bcc.	(666)	1		
5-41	Delay time	dELy.	(9EFA)	20		
5-42	Communication memory mode	mEm.	(ភ៩ភ)	EEP		
5-43	Keylock	LocK.	(Locy)	oFF		

	100%										
Pattern No.											
Start SV	ł										
Start OV	90										
The number of	1										
steps											
TS1 ON step	80										
TS1 ON time	ł										
	70										
TS1 OFF step											
TO4 OFF ::	1										
TS1 OFF time	60										
	60										
TS2 ON step	1										
102 014 3100											
TS2 ON time	50										
TS2 OFF step											
	40										
TS2 OFF time	40										
132 OFF UITIE											
EV1 setting	1										
	30										
EV2 setting											
EV3 setting	20										
Evs seumg	20										
The number of	1										
pattern executions											
_	10										
Guarantee soak											
PV start	ł										
, v start	0										
Step No.		1	2	3	4	5	6	7	8	9	10
SV (set value)											
Time											
PID No. (0~6)											

PID No.	1	2	3	4	5	6
Р						
I						
D						
Hysteresis						
MR						
Target value function						
Higher limit of output limiter		-				
Lower limit of output limiter						

Zone PID	
Zone PID ON/OFF	
Zone 1 SP	
Zone 2 SP	
Zone 3 SP	
Zone hysteresis	

[★] Copy these pages for your use as occasion demands.

9. Specifications

■ Display Display means Digital display : PV Red 7 segments LED 4 digits Green 7 segments LED 4 digits : SV : PTN Green 7 segments LED 1 digit Green 7 segments LED 2 digits : STEP Status display : OUT Green LED lamp indication : EV1~3 (3 points) Orange LED lamp indication Green LED lamp indication : AT : MAN Green LED lamp indication : COM Green LED lamp indication Green LED lamp indication : DO1~4 (4 points) Green LED lamp indication ·GUA : RUN Green LED lamp indication (blinks during FIX) : HLD Green LED lamp indication : → "ascend" Green LED lamp indication $: \longrightarrow$ "level" Green LED lamp indication : >> "descend" Green LED lamp indication Display accuracy : $\pm (0.3\% FS + 1 \text{ digit})$, with restriction depending on measuring range, CJ error excluded. Display accuracy maintaining range : 23°C±5°C : Differs by measuring range (0.001, 0.01, 0.1 and 1) Display resolution Measured value display range : -10%~110% of measuring range (-210~680°C for Pt -200~600°C range) Display updating cycle : 0.25 second • Input scaling : Possible during linear input (current and voltage) (-1999~9999, span 10~5000, decimal point position variable) ■ Setting : Operated by 8 keys $(\bigcirc, \bigvee, \bigwedge, (ENT), (GRP), (PTN), (STEP), (NYSTEP))$ on the front panel Local Setting SV setting range : Same as measuring range (within setting limiter) Setting limiter : Individual setting for higher and lower limits, any value is selectable within measuring range (Lower limit < Higher limit) Keylock : OFF, 1~3 (4 levels) Setting of unit : °C or °F selectable for sensor input ■ Input Type of input : Selectable from multiple (TC, Pt, mV, V) and current (mA) Thermocouple : Input impedance 500 k Ω minimum : External resistance tolerance $100~\Omega$ maximum : Influence of lead wire tolerance $1.2\mu V/10~\Omega$: Burnout function standard up scale Within the accuracy maintaining range ±1°C : Cold junction compensation accuracy Ambient temperature 5~45°C ±2°C *1 : For K, T and U thermocouples with indication values below -100° C, $\pm 0.7\%$ FS *2 : Accuracy guarantee not applicable to B thermocouple below 400°C (752°F). ● R.T.D. : Normal current: 0.25 mA : Lead wire tolerance 5 Ω maximum/wire (3 lead wires should have the same resistance.) Influence of lead wire tolerance (error in temperature) 0.3° C maximum in the case of 5 Ω /wire 0.7° C maximum in the case of 10Ω /wire 1.6° C maximum in the case of 20Ω /wire Voltage : Input impedance 500 k Ω minimum : mA to be taken care of by external resistor 250 Ω Current Sampling cycle : 0.25 second PV filter : 0~100 seconds PV bias : -1999~2000 units Isolation : Not insulated from system and DI but insulated from others ■ Control Control mode : Expert PID control with auto tuning function RA (heating)/DA (cooling) action ● Type of control output/rating : Contact 1c 240V AC 2.5A(resistive load) 1.0A (inductive load) SSR drive voltage12V±1.5V DC (Maximum load current 30mA) Current 4~20mA (Maximum load resistance 600 Ω) Voltage 0~10V (Maximum load current 2mA) Resolution : About 1/8000

: ±1.0% FS (5~100%)

Accuracy of output

● Control output Proportional band (P) : OFF or 0.1~999.9% FS (ON-OFF action by OFF)

Integral time (I) : OFF or 1~6000 seconds (P or PD action by OFF)

Derivative time (D) : OFF or 1~3600 seconds (P or PI action by OFF)

Target value function : OFF or 0.01~1.00 ON/OFF hysteresis : 1~999 units

Manual reset : $\pm 50.0\%$ (Effective when I = OFF)

Output limiter : Lower limit 0.0~99.9%, higher limit 0.1~100.0%

Proportional cycle : 1~120 seconds (when contact and SSR drive voltage output)

Manual control : 0.0~100.0% Setting resolution 0.1

■ Control output characteristic : RA/DA to be set by front key

■ Isolation : Contact output insulated from all

AO (analog output) not insulated from SSR drive voltage, current or voltage output but insulated from

others

■ External control input (DI)

Number of input points : 4

• Type of input : Edge or level input (none, RUN/RST, HLD, ADV, FIX and start pattern No.)

DI1 fixed to RUN/RST for DI2~4, selectable from none, RUN/RST, HLD, ADV, FIX and start pattern

No.)

● Input rating : Voltage 5V DC (0.5mA/1 input)
● Input holding time : Minimum 0.125 seconds

Isolation : Not insulated from input and system but insulated from others.

• Action input : No-voltage contact or open collector

■ Event output

Contact output rating
 Normal open (1a × 3 common) 240V AC 1A (resistive load)

• Action : ON-OFF action

• Hysteresis : 1~999 units (during alarm output)

• Types : Selectable from the following 16 types respectively for EV1, EV2 and EV3

No selection, Higher limit deviation, Lower limit deviation, Outside higher/lower limit deviations, Within higher/lower limit deviations, Higher limit absolute value, Lower limit absolute value, Scaleover, Hold, Guarantee soak, Time signal (2 types), RUN status, step signal, End signal, FIX

• Event setting range:

Absolute value alarm: Within measuring range

Deviation alarm: Higher limit deviation -1999~2000 units, lower limit deviation -1999~2000 units

Outside higher/lower limit deviations : $0\sim2000$ units Within higher/lower limit deviations : $0\sim2000$ units

Standby action : Selectable from the following 4 types respectively for EV1, EV2 and EV3

: None, Standby 1 (standby only when power is applied), Standby 2 (standby when power is applied and when SV in execution is changed), and Standby 3 (input abnormality not output [Control mode])

• Output updating cycle : 0.25 second

• Isolation : Insulated from other inputs

■ Communication function (option)

● Type of communication : RS-232C or RS-485

• Communication system : RS-232C/3-line type half duplex system, RS-485/2-line type half duplex multi-drop (bus) system

• Synchronization system : Start-stop synchronization system

● Communication distance : RS-232C/Max. 15m, RS-485/Max. 500m (depending on conditions)

● Communication address : 1~255

● Communication speed : 1200, 2400, 4800, 9600, 19200 bps

● Data format : 7 bits, even parity, 1 stop bit or 8 bits, non-parity, 1 stop bit

● Communication delay : 1~100 (0.512msec/unit)

 $lacktriangled{\bullet} \mbox{Communication BCC} : \mbox{Selectable from Addition (ADD), Addition} + \mbox{two's complement (ADD_two's cmp)}, \mbox{ Exclusive OR}$

(XOR) and (None)

● Communication memory mode : Selectable from EEP, rAm and r_E

• Communication code : ASCII code

• Communication protocol : Shimaden's standard protocol

● Number of connectable instruments : 1 for RS-232C, 31 for RS-485 (Address setting 1~255)

Isolation : insulated from other inputs and outputs

• Others : Start character and BCC operation method also selectable

■ Analog output (option)

• Number of output points : 1

• Type of analog output : Selectable from measured value, target value (SV in execution) and control output

lacktriangle Output specification/rating : Current 4~20mA DC (Maximum load resistance 300 Ω)

Voltage 0~10V DC (Maximum load resistance 2mA)

0~10mV DC (Output resistance 10 Ω)

lacktriangle Output accuracy when measured value is output $\pm 0.6\%$ FS (Comprehensive accuracy when measured value is output $\pm 0.6\%$ FS)

Scaling : Within measuring range or output range (inversed scaling possible)

Output resolution : About 1/10000Output updating cycle : 0.25 second

Isolation : Not insulated from P.I.V. control output but insulated from others

■ Status output (DO) (option)

• Number of output points : 4

● Type of output : None, scaleover, hold, guarantee soak, time signal (2 types), RUN status, step signal, end signal, FIX

Output specification/rating
 Open collector darlington output, voltage 24V DC (maximum load current 20mA), saturation voltage

during status output ON 1.2V

• Output updating cycle : 0.25 second

• Isolation : Insulated from other inputs and outputs

■ Program

Number of patterns
 : Maximum 4 (setting 1, 2 or 4 possible)
 Number of steps
 : Maximum 10~40 (Total number of steps = 40)

Number of PID types : Maximum 6
 Number of zone PID types : Maximum 3
 Zone hysteresis : 0~999 units

• Time setting : 0 hour 0 minute~99 hours 59 minutes or 0 minute 0 second~99 minutes 59 seconds/1 step

• Setting resolution : 1 minute or 1 second

• Accuracy of time $: \pm \text{ (set time} \times 0.02\% + 0.25 \text{ second)}$ • Setting for each step : SV, step time and PID No.

• Time signal : 2 outputs/pattern, to be set within time setting range

Number of pattern executions
 ∴ Maximum 9999
 ∴ PV start
 ∴ ON/OFF
 → Guarantee soak
 ∴ OFF, 1~999 units

Hold : Front key input or external control input
Advance : Front key input or external control input

Power failure compensation
 : ON/OFF (guarantee not applicable to the period of time of step in which power failure occurs)

■ General specification

Data storage : Non-volatile memory (EEPROM)

• Environmental conditions for instrument operation:

Temperature $:-10\sim50^{\circ}\text{C}$

Humidity : 90% RH or less (no dew condensation) Height : 2000m from the sea level or lower

Category : II Degree of pollution : 2

• Storage temperature $: -20\sim65^{\circ}C$

● Supply voltage : 100~240V AC±10% 50/60Hz

24V AC/DC±10% (option)

● Input/noise removal ratio : 50 dB or higher in normal mode (50/60 Hz)

130 dB or higher in common mode (50/60 Hz)

lacktriangle Insulation resistance : Between input/output terminals and power terminal 500V DC 20 M Ω or above

Between input/output terminals and protective conductor terminal 500V DC 20 $M\Omega$ or above

• Dielectric strength : Between input/output terminals and power terminal 2300V AC/minute

Between power terminal and protective conductor terminal 1500V AC/minute

● Power consumption : 16VA maximum for AC, 7W for DC

Conformity with standards

Safety : IEC61010-1 and EN61010-1

EMC : EN61326

Protective structure
 : Only front panel has dust-proof and drip-proof structure equivalent to IP66.

● Material of case : PPO (equivalent to UL94V-1)

● External dimensions : H96 × W96 × D111mm (Panel depth: 100)

◆ Panel thickness : 1~4mm
 ◆ Mounting dimensions : H92 × W92mm
 ◆ Weight : Approximately 450g

The contents of this manual are subject to change without notice.

Temperature and Humidity Control Specialists

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